

**IN THE SPECIFICATION**

Please replace paragraph 37 as originally filed with the following:

[0037] Referring to Fig. 3, a diagram is shown of a method for registering a representation of probe 56 with an image using feature 116. At step ~~152~~ 150, probe 56 is used to locate feature 116 on interior surface 118 of heart 72. In one embodiment, this is done by person 58 who moves probe 56 until feature 116 is located based on its electrical properties (e.g., scar tissue having zero conductivity, etc.). Typically, probe 56, and specifically, sensor 76 contact feature 116 during step ~~152~~ 150. Referring back to Fig. 3, once feature 116 has been located, the location of probe 56 is sensed at step 152. The location is stored in system 50 and/or displayed on display 52. Typically, the location of probe 56 is sensed using a localization system, which may be included as part of system 50.

Please replace paragraph 41 as originally filed with the following:

[0041] Referring back to Fig. 3, once the location of feature 116 has been determined, the representation of probe 56 is registered with feature 116 in the image at step 154. In one embodiment, this may be done by a user such as a person 58 who visually locates feature 116 in the image and registers the representation of probe 56 to feature 116 displayed in the image. For example, system 50 may be configured so that the user can select the representation of probe 56 on display 52 and drag and drop the representation on feature 116 shown in the image. The location of probe 56 and the image are now registered at that feature. Of course, other methods may be used to register the location of probe 56 with feature 116 in the image. Once one representation of probe 56 has been registered with the image, steps 150-154 may be repeated for additional features 116 thereby registering the image with a number of the representations of probe 56. In an exemplary embodiment, it is desirable to register the image with at least three representations of probe 56.